

Ergodic theory and linear dynamics

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Ergodic theory

Let (X, \mathcal{B}, μ) be a probability space and let $T : (X, \mathcal{B}, \mu) \rightarrow (X, \mathcal{B}, \mu)$ be a measurable map.

Definition

- (a) T is called a **measure-preserving transformation** if $\mu(T^{-1}(A)) = \mu(A)$ for all $A \in \mathcal{B}$.
- (b) T is called **ergodic** if it is measure-preserving and satisfies one of the following equivalent conditions:
 - (i) Given any measurable sets A, B with positive measures, one can find an integer $n \geq 0$ such that $T^n(A) \cap B \neq \emptyset$;
 - (ii) if $A \in \mathcal{B}$ satisfies $T(A) \subset A$, then $\mu(A) = 0$ or 1.

Example - Irrational rotations

Let $X = \mathbb{T}$, let \mathcal{B} be the Borel σ -algebra on \mathbb{T} and let μ be the Lebesgue measure on \mathbb{T} . Let $\theta \in \mathbb{R} \setminus \mathbb{Q}$. Then

$$\begin{aligned} T : (X, \mathcal{B}, \mu) &\rightarrow (X, \mathcal{B}, \mu) \\ z &\mapsto e^{i2\pi\theta} z \end{aligned}$$

is ergodic.

Example - Dyadic transformation

Let $X = [0, 1)$, let \mathcal{B} be the Borel σ -algebra on X and let μ be the Lebesgue measure on X . Then

$$\begin{aligned} T : (X, \mathcal{B}, \mu) &\rightarrow (X, \mathcal{B}, \mu) \\ x &\mapsto 2x \bmod 1 \end{aligned}$$

is ergodic.

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μ_k is defined by $\mu_k(\{1\}) = 1/2$ and $\mu_k(\{-1\}) = 1/2$. Let $\mu = \dots \otimes \mu_{-1} \otimes \mu_0 \otimes \mu_1 \otimes \dots$, namely

$$\mu(\{x \in X; (x_n, \dots, x_p) \in E_n \times \dots \times E_p\}) = \mu_n(E_n) \times \dots \times \mu_p(E_p).$$

Then

$$\begin{aligned} T : (X, \mathcal{B}, \mu) &\rightarrow (X, \mathcal{B}, \mu) \\ (x_n) &\mapsto (x_{n+1}) \end{aligned}$$

is ergodic.

Why?

STRATEGY: Let $T \in \mathcal{L}(X)$. Suppose that we can construct a measure μ defined on the Borel σ -algebra \mathcal{B} of X , such that

- μ has **full support** (namely $\mu(U) > 0$ for any non-empty open set $U \subset X$);
- T is ergodic with respect to μ (namely $\mu(A)\mu(B) \neq 0$ implies that there exists $n \in \mathbb{N}$ with $T^n(A) \cap B \neq \emptyset$.)

Then T is topologically transitive, hence hypercyclic.

Birkhoff's ergodic theorem

Theorem

Let (X, \mathcal{B}, μ) be a probability space and let

$T : (X, \mathcal{B}, \mu) \rightarrow (X, \mathcal{B}, \mu)$ be a measure-preserving ergodic transformation. For any $f \in L^1(X, \mu)$,

$$\frac{1}{N} \sum_{n=0}^{N-1} f(T^n x) \xrightarrow{N \rightarrow \infty} \int_X f d\mu \quad \mu\text{-a.e.}$$

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Corollary

Let $T \in \mathfrak{L}(X)$. Assume that T is an ergodic transformation with respect to a Borel probability measure μ on X with full support.

Then μ -almost every point $x \in X$ has the following property: for every non-empty open set $V \subset X$, one has

$$\liminf_{N \rightarrow \infty} \frac{\text{card} \{n \in [0, N); T^n(x) \in V\}}{N} > 0.$$

Thus, if we can construct a probability measure μ defined on the Borel σ -algebra \mathcal{B} of X , such that

- μ has **full support** (namely $\mu(U) > 0$ for any non-empty open set $U \subset X$);
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Hypercyclic operators satisfying the stronger condition (1) are called **frequently hypercyclic**. Moreover, we get that the set of (frequently) hypercyclic vectors is large in a probabilistic sense.

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- Given $T \in \mathfrak{L}(X)$ and a measure μ on X , how to prove that T is ergodic with respect to μ ?
- What kind of conditions on $T \in \mathfrak{L}(X)$ ensures that we can construct a measure μ on X such that the dynamical system (T, μ) is ergodic?

Real Gaussian variables

For any $\sigma > 0$, let us denote by γ_σ the centered Gaussian measure on \mathbb{R} with variance σ^2 ; that is,

$$d\gamma_\sigma = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{t^2}{2\sigma^2}} dt.$$

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$$\left. \begin{array}{l} X_1 \sim \gamma_{\sigma_1} \\ X_2 \sim \gamma_{\sigma_2} \\ X_1 \text{ and } X_2 \text{ are independent} \end{array} \right\} \implies X_1 + X_2 \sim \gamma_\sigma \text{ with } \sigma^2 = \sigma_1^2 + \sigma_2^2.$$

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If (X_n) are independent random variables, $X_n \sim \gamma_{\sigma_n}$ and if $\sum_n \sigma_n^2 < +\infty$, then $\sum_n X_n \sim \gamma_\sigma$ with $\sigma^2 = \sum_n \sigma_n^2$.

Complex Gaussian variables

Definition

A complex-valued random variable $Z : \Omega \rightarrow \mathbb{C}$ defined on some probability space $(\Omega, \mathcal{F}, \mathbb{P})$ is said to have **complex symmetric Gaussian distribution** if either Z is almost surely 0, or the real and imaginary parts of Z are independent and have centered Gaussian distribution with the same variance.

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Remark

Let Z be a complex random variable with complex Gaussian distribution, $\mathbb{E}(|Z|^2) = \sigma^2$, and write it $Z = X + iY$. Then $\mathbb{E}(|X|^2) = \sigma^2/2$ and $\mathbb{E}(|Y|^2) = \sigma^2/2$. If $\mathbb{E}|Z|^2 = 1$, then Z is said to be **standard**.

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Remark

Suppose that Z has complex symmetric Gaussian distribution. Then, for any $\lambda \in \mathbb{C}$, λZ has complex symmetric Gaussian distribution and $\mathbb{E}(|\lambda Z|^2) = |\lambda|^2 \mathbb{E}(|Z|^2)$.

Gaussian measures

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Let $(\Omega, \mathcal{F}, \mathbb{P})$ be a probability space, and let $(g_n)_{n \in \mathbb{N}}$ be a sequence of independent standard complex Gaussian variables defined on $(\Omega, \mathcal{F}, \mathbb{P})$. Such a sequence (g_n) will be called a **standard Gaussian sequence**.

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Definition

A **Gaussian sum** in X is a sum $\sum_n g_n x_n$ where (x_n) is a sequence of vectors in X .

Convergence of Gaussian sums

Proposition

Let $(x_n) \subset X$. The following are equivalent :

- (i) The Gaussian sum $\sum_n g_n x_n$ converges almost surely.
- (ii) The Gaussian sum $\sum_n g_n x_n$ converges in L^p , for some $p \in [1, +\infty)$;
- (iii) The Gaussian sum $\sum_n g_n x_n$ converges in L^p , for any $p \in [1, +\infty)$;
- (iv) The Gaussian sum $\sum_n g_n x_n$ converges in probability.

If X is a Hilbert space, this is equivalent to $\sum_n \|x_n\|^2 < +\infty$.

Distribution of a Gaussian sum

The distribution of the Gaussian sum $\sum_n g_n x_n$ is defined by

$$\mu(A) = \mathbb{P} \left(\left\{ \omega \in \Omega; \sum_n g_n(\omega) x_n \in A \right\} \right).$$

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If the series $\sum_n g_n x_n$ is almost surely convergent, then its distribution is a Gaussian measure.

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- Step 1: the same result on \mathbb{R} .

If (X_n) are independent random variables, $X_n \sim \gamma_{\sigma_n}$ and if $\sum_n \sigma_n^2 < +\infty$, then $\sum_n X_n \sim \gamma_\sigma$ with $\sigma^2 = \sum_n \sigma_n^2$.

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- Step 2: the same result on \mathbb{C} .

Lemma

Let (a_n) be a sequence of complex numbers such that $\sum_n |a_n|^2 < +\infty$. Then $\sum_n g_n a_n$ has complex symmetric Gaussian distribution.

Distribution of Gaussian sums are Gaussian measures

Theorem

If the series $\sum_n g_n x_n$ is almost surely convergent, then its distribution is a Gaussian measure.

Proof.

Let $x^* : (X, \mathcal{B}, \mu) \rightarrow (\mathbb{C}, \mathcal{B}(\mathbb{C}))$ and let $A \in \mathcal{B}(\mathbb{C})$. Does x^* has symmetric complex Gaussian distribution?

$$\begin{aligned}\mu(x^{*-1}(A)) &= \mathbb{P} \left(\left\{ \omega \in \Omega; \left\langle x^*, \sum_n g_n x_n \right\rangle \in A \right\} \right) \\ &= \mathbb{P} \left(\left\{ \omega \in \Omega; \sum_n g_n \langle x^*, x_n \rangle \in A \right\} \right)\end{aligned}$$

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...and by the lemma $\sum_n g_n \langle x^*, x_n \rangle$ has complex symmetric Gaussian distribution. □

The covariance operator

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Theorem

Let μ be a Gaussian measure on X .

- (1) *One can define a continuous, conjugate-linear operator $R_\mu : X^* \rightarrow X$ such that, for every $(x^*, y^*) \in X^* \times X^*$:*

$$\langle R_\mu(x^*), y^* \rangle = \int_X \overline{\langle x^*, z \rangle} \langle y^*, z \rangle d\mu(z) = \langle x^*, y^* \rangle_{L^2(\mu)}.$$

*The operator R_μ is called the **covariance operator** of μ .*

- (2) *Two Gaussian measures on X coincide if and only if they have the same covariance operator.*

Factorisation of the covariance operator

$$\langle R_\mu(x^*), y^* \rangle = \int_X \overline{\langle x^*, z \rangle} \langle y^*, z \rangle d\mu(z) = \langle x^*, y^* \rangle_{L^2(\mu)}.$$

- R_μ is symmetric: $\langle R_\mu(x^*), y^* \rangle = \overline{\langle x^*, R_\mu(y^*) \rangle}$;
- R_μ is positive: $\langle R_\mu(x^*), x^* \rangle \geq 0$.

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- R_μ is symmetric: $\langle R_\mu(x^*), y^* \rangle = \overline{\langle x^*, R_\mu(y^*) \rangle}$;
- R_μ is positive: $\langle R_\mu(x^*), x^* \rangle \geq 0$.

There exists some separable Hilbert space \mathcal{H} and an operator $K : \mathcal{H} \rightarrow X$ such that

$$R_\mu = KK^*.$$

Covariance operator and properties of μ

$$\langle R_\mu(x^*), y^* \rangle = \int_X \overline{\langle x^*, z \rangle} \langle y^*, z \rangle d\mu(z) = \langle x^*, y^* \rangle_{L^2(\mu)}.$$

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Theorem

Let μ be a Gaussian measure and let $R = KK^$ be its covariance operator. Then the following properties are equivalent :*

- (i) μ has full support;
- (ii) R is one-to-one;
- (iii) K has dense range.

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The difficult implication: (iii) \implies (i).

Gaussian measures with full support

K has dense range $\implies \mu$ has full support.

Step 1 The support of a Gaussian sum.

Let $\sum_n g_n x_n$ be an almost surely convergent Gaussian sum and let ν be its distribution. Let $O \subset X$ be open such that $O \cap \text{span}(x_n) \neq \emptyset$. Then $\nu(O) > 0$.

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The support of the distribution of a Gaussian sum $\sum_n g_n x_n$ is the closure of $\text{span}(x_n)$.

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Step 2 The covariance operator of a Gaussian sum.

Let $\sum_n g_n x_n$ be an almost surely convergent Gaussian sum and let ν be its distribution. Then the covariance operator of ν is given by

$$R_\nu(x^*) = \sum_n \overline{\langle x^*, x_n \rangle} x_n.$$

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$$\begin{aligned} \langle R_\nu(x^*), y^* \rangle &= \int_X \overline{\langle x^*, x \rangle} \langle y^*, x \rangle d\nu(x) \\ &= \int_\Omega \overline{\left\langle x^*, \sum_n g_n(\omega) x_n \right\rangle} \left\langle y^*, \sum_n g_n(\omega) x_n \right\rangle d\mathbb{P}(\omega) \\ &= \sum_{n,m} \overline{\langle x^*, x_n \rangle} \langle y^*, x_m \rangle \int_\Omega \overline{g_n(\omega)} g_m(\omega) d\mathbb{P}(\omega) \\ &= \sum_n \overline{\langle x^*, x_n \rangle} \langle y^*, x_n \rangle \end{aligned}$$

Gaussian measures with full support

Step 3 Any Gaussian measure is the distribution of a Gaussian sum

Let $R = KK^*$ be the covariance operator of some Gaussian measure μ . Then, for any orthonormal basis (e_n) of \mathcal{H} ,

$$Rx^* = \sum_n \overline{\langle x^*, Ke_n \rangle} Ke_n.$$

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$$\begin{aligned} R(x^*) &= K \left(\sum_{n=0}^{\infty} \langle e_n, K^*(x^*) \rangle_{\mathcal{H}} e_n \right) \\ &= \sum_{n=0}^{\infty} \overline{\langle x^*, K(e_n) \rangle} K(e_n), \end{aligned}$$

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Measure-preserving transformations

Proposition

Let μ be a Gaussian measure on X with covariance operator R and let $T \in \mathcal{L}(X)$. Then the image measure $\mu_T = \mu \circ T^{-1}$ is a Gaussian measure on X , with covariance operator TRT^* . In particular, T is measure-preserving if and only if $TRT^* = R$.

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$$\begin{aligned}\langle R_T(x^*), y^* \rangle &= \int_Y \overline{\langle x^*, z \rangle} \langle y^*, z \rangle d\mu_T(z) \\ &= \int_X \overline{\langle x^*, T(z) \rangle} \langle y^*, T(z) \rangle d\mu(z) \\ &= \langle RT^*x^*, T^*y^* \rangle \\ &= \langle TRT^*(x^*), y^* \rangle.\end{aligned}$$

What about ergodicity?

$T : (X, \mathcal{B}, \mu) \rightarrow (X, \mathcal{B}, \mu)$ is ergodic provided

$$\forall (A, B) \in \mathcal{B}, \mu(A)\mu(B) \neq 0 \implies \exists n \in \mathbb{N}, T^n(A) \cap B \neq \emptyset.$$

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Birkhoff's theorem says that for an ergodic transformation T ,

$$\frac{1}{N} \sum_{n=0}^{N-1} f(T^n x) \xrightarrow{N \rightarrow \infty} \int_X f d\mu \quad \mu\text{-a.e.}$$

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$$\frac{1}{N} \sum_{n=0}^{N-1} f(T^n x) \xrightarrow{N \rightarrow \infty} \int_X f d\mu \quad \mu\text{-a.e.}$$

Thus, $T : (X, \mathcal{B}, \mu) \rightarrow (X, \mathcal{B}, \mu)$ is ergodic

$$\iff \forall f, g \in L^2(X, \mu), \frac{1}{N} \sum_{n=0}^{N-1} \int_X f(T^n x) g(x) d\mu \xrightarrow{N \rightarrow \infty} \int_X f d\mu \int_X g d\mu,$$

What about ergodicity?

$T : (X, \mathcal{B}, \mu) \rightarrow (X, \mathcal{B}, \mu)$ is ergodic provided

$$\forall (A, B) \in \mathcal{B}, \mu(A)\mu(B) \neq 0 \implies \exists n \in \mathbb{N}, T^n(A) \cap B \neq \emptyset.$$

Birkhoff's theorem says that for an ergodic transformation T ,

$$\frac{1}{N} \sum_{n=0}^{N-1} f(T^n x) \xrightarrow{N \rightarrow \infty} \int_X f d\mu \quad \mu\text{-a.e.}$$

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$$\iff \forall A, B \in \mathcal{B}, \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{n=0}^{N-1} \mu(T^n A \cap B) = \mu(A)\mu(B).$$

Weakly mixing - Strongly mixing

$T : (X, \mathcal{B}, \mu) \rightarrow (X, \mathcal{B}, \mu)$ is **weakly mixing**

$$\iff \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{n=0}^{N-1} |\mu(A \cap T^{-n}(B)) - \mu(A)\mu(B)| = 0 \quad (A, B \in \mathcal{B})$$

$$\iff \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{n=0}^{N-1} \left| \int_X f(T^n z) g(z) d\mu(z) - \int_X f d\mu \int_X g d\mu \right| = 0.$$

$T : (X, \mathcal{B}, \mu) \rightarrow (X, \mathcal{B}, \mu)$ is **strongly mixing**

$$\iff \lim_{n \rightarrow \infty} \mu(A \cap T^{-n}(B)) = \mu(A)\mu(B) \quad (A, B \in \mathcal{B})$$

$$\iff \lim_{n \rightarrow \infty} \int_X f(T^n z) g(z) d\mu(z) = \int_X f d\mu \int_X g d\mu \quad (f, g \in L^2(X, \mu)).$$

The characterization of mixing properties

Theorem (Rudnicki, 1993)

Let μ be a Gaussian measure on X with full support and covariance operator R . Let $T \in \mathfrak{L}(X)$ be measure-preserving. The following are equivalent:

- (i) T is weakly mixing (strongly mixing, respectively) with respect to μ ;
- (ii) For all $x^*, y^* \in X^*$,

$$\lim_{N \rightarrow \infty} \frac{1}{N} \sum_{n=0}^{N-1} |\langle RT^{*n}(x^*), y^* \rangle| = 0$$

($\lim_{n \rightarrow \infty} \langle RT^{*n}(x^*), y^* \rangle = 0$, respectively).

The easy implication

- (i) T is strongly mixing with respect to μ , namely

$$\lim_{n \rightarrow \infty} \int_X f(T^n z) g(z) d\mu(z) = \int_X f d\mu \int_X g d\mu \quad (f, g \in L^2(X, \mu)).$$

- (ii) For all $x^*, y^* \in X^*$, $\lim_{n \rightarrow \infty} \langle RT^{*n}(x^*), y^* \rangle = 0$.

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- (ii) For all $x^*, y^* \in X^*$, $\lim_{n \rightarrow \infty} \langle RT^{*n}(x^*), y^* \rangle = 0$.

$$\langle R(x^*), y^* \rangle = \int_X \overline{\langle x^*, z \rangle} \langle y^*, z \rangle d\mu(z).$$

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$$\langle RT^{*n}(x^*), y^* \rangle \rightarrow \int_X \overline{\langle x^*, z \rangle} d\mu(z) \int_X \langle y^*, z \rangle d\mu(z) = 0.$$

The difficult implication - I

Assumption:

$$\lim_{n \rightarrow \infty} \langle RT^{*n}(x^*), y^* \rangle = 0 \quad (x^*, y^*) \in X^*.$$

Conclusion:

$$\lim_{n \rightarrow \infty} \mu(A \cap T^{-n}(B)) = \mu(A)\mu(B) \quad (A, B \in \mathcal{B}). \quad (2)$$

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Definition

$A \subset X$ is a **cylinder set** if there exist $N \geq 1$, (x_1^*, \dots, x_N^*) a family of independent vectors of X^* and $E \subset \mathbb{C}^N$ such that

$$A = \{x \in X; (\langle x_1^*, x \rangle, \dots, \langle x_N^*, x \rangle) \in E\}.$$

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It suffices to testify (2) for A, B cylinder sets.

The difficult implication - II

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Cylinder sets are "finite-dimensional sets"

The difficult implication - II

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Cylinder sets are "finite-dimensional sets" \implies we need a finite-dimensional lemma.

Lemma

Let (ν_n) be a sequence of Gaussian measures on some finite-dimensional Banach space $E = \mathbb{C}^N$, and let ν be a Gaussian measure on E with full support. Assume that $R_{\nu_n} \rightarrow R_\nu$ as $n \rightarrow \infty$. Then $\nu_n(Q) \rightarrow \nu(Q)$ for every Borel set $Q \subset E$.

The difficult implication - III

Assumption:

$$\lim_{n \rightarrow \infty} \langle RT^{*n}(x^*), y^* \rangle = 0 \quad (x^*, y^*) \in X^*.$$

$$\begin{aligned} A &= \{x \in X; (\langle x_1^*, x \rangle, \dots, \langle x_N^*, x \rangle) \in E\} \\ B &= \{x \in X; (\langle y_1^*, x \rangle, \dots, \langle y_M^*, x \rangle) \in F\}. \end{aligned}$$

Aim :

$$\lim_{n \rightarrow \infty} \mu(A \cap T^{-n}(B)) = \mu(A)\mu(B).$$

Tool :

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Questions to solve

- What kind of measures shall we consider?
- Given $T \in \mathfrak{L}(X)$ and a measure μ on X , how to prove that T is a measure-preserving transformation?
- Given $T \in \mathfrak{L}(X)$ and a measure μ on X , how to prove that T is ergodic with respect to μ ?
- What kind of conditions on $T \in \mathfrak{L}(X)$ ensures that we can construct a measure μ on X such that the dynamical system (T, μ) is ergodic?

Having sufficiently many \mathbb{T} -eigenvectors

Definition

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Definition

A map $E : \mathbb{T} \rightarrow X$ is a **perfectly spanning \mathbb{T} -eigenvector field** provided

- (i) $E \in L^\infty(\mathbb{T}, X)$;
- (ii) $\forall \lambda \in \mathbb{T}, TE(\lambda) = \lambda E(\lambda)$;
- (iii) For any $A \subset \mathbb{T}$ with $m(A) = 0$, then $\text{span}(E(\lambda); \lambda \in A)$ is dense in A .

The operator K_E

Let $T \in \mathfrak{L}(X)$ with a perfectly spanning \mathbb{T} -eigenvector field E .
Define

$$\begin{aligned} K_E : L^2(\mathbb{T}, dm) &\rightarrow X \\ f &\mapsto \int_{\mathbb{T}} f(\lambda) E(\lambda) dm(\lambda) \end{aligned}$$

and $R = K_E K_E^*$. Then

1. K_E has dense range;
2. $TRT^* = T$;
3. For any $x^*, y^* \in X^*$, $\langle RT^{*n}(x^*), y^* \rangle \rightarrow 0$.

The intertwining equation

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$$TK = KV.$$

$$\begin{aligned} TK_E(f) &= \int_{\mathbb{T}} f(\lambda) TE(\lambda) dm(\lambda) \\ &= \int_{\mathbb{T}} f(\lambda) \lambda E(\lambda) dm(\lambda) \\ &= KVf. \end{aligned}$$

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Ok for R !

Is R the covariance operator of some Gaussian measure μ ?

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Proposition

Let $K \in \mathfrak{L}(\mathcal{H}, X)$ be γ -radonifying. Then $R = KK^*$ is the covariance operator of some Gaussian measure μ on X .

It suffices to take for μ the distribution of the Gaussian sum $\sum_n g_n K e_n$.

On a Hilbert space

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Fact. On a Hilbert space, a Gaussian sum $\sum_n g_n x_n$ converges almost surely if and only if $\sum_n \|x_n\|^2 < +\infty$.

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It is Hilbert-Schmidt!

$R = K_E K_E^*$ is the covariance operator of some Gaussian measure!

Theorem on a Hilbert space

Theorem (B. Grivaux (2006))

Let X be a separable Hilbert space and let $T \in \mathcal{L}(X)$ be such that T has a perfectly spanning \mathbb{T} -eigenvectorfield. Then there exists a Gaussian measure μ on X with full support, with respect to which T is a strongly-mixing measure-preserving transformation.

What about Banach spaces?

$K \in \mathfrak{L}(\mathcal{H}, X)$ is γ -radonifying if for some orthonormal basis (e_n) of \mathcal{H} , the Gaussian series $\sum g_n(\omega)K(e_n)$ converges almost surely.

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Definition

A Banach space X is said to have (Gaussian) **type** $p \in [1, 2]$ if

$$\left\| \sum_n g_n x_n \right\|_{L^2(\Omega, X)} \leq C \left(\sum_n \|x_n\|^p \right)^{\frac{1}{p}},$$

for some finite constant C and every finite sequence $(x_n) \subset X$.

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- A Hilbert space has type 2;
- L^p -spaces have type $\min(p, 2)$;
- Any Banach space has type 1;

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Corollary

Let X be a Banach space with type p and let $K \in \mathfrak{L}(\mathcal{H}, X)$. Then K is γ -radonifying as soon as $\sum_n \|Ke_n\|^p < +\infty$ for some orthonormal basis (e_n) of \mathcal{H} .

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Theorem (B. Matheron, 2009)

Let X be a separable Banach space and let $T \in \mathfrak{L}(X)$ be such that T has a perfectly spanning \mathbb{T} -eigenvector field E . Suppose moreover that :

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- (e_n) = the Haar basis of $L^2(\mathbb{T})$.

Banach spaces=Hilbert spaces!

Theorem (B. 2011)

Let X be a separable Banach space and let $T \in \mathfrak{L}(X)$ be such that T has a perfectly spanning \mathbb{T} -eigenvector field. Then there exists a Gaussian measure μ on X with full support, with respect to which T is a weakly-mixing measure-preserving transformation.

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Strategy. Instead of considering

$$K_E : L^2(\mathbb{T}, dm) \rightarrow X,$$

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with σ a continuous measure on \mathbb{T} .

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with σ a continuous measure on \mathbb{T} . σ will be carried on **Cantor set!**

Cantor sets

Definition

A subset \mathcal{C} of \mathbb{T} is a **Cantor set** if it is the continuous image of $\{-1, 1\}^{\mathbb{N}}$.

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$\{-1, 1\}^{\mathbb{N}}$ will be endowed with its Haar measure ν . ν is the tensor product $\mathbb{P}_1 \otimes \mathbb{P}_2 \otimes \dots$, with, one each coordinate,

$$\mathbb{P}_k(\{-1\}) = 1/2 \text{ and } \mathbb{P}_k(\{1\}) = 1/2.$$

An orthonormal basis of $L^2(\{-1, 1\}^\omega)$.

Any $\omega \in \{-1, 1\}^\mathbb{N}$ can be written

$$\omega = (\varepsilon_1(\omega), \varepsilon_2(\omega), \dots).$$

Definition

Let $A \subset \mathcal{P}_f(\mathbb{N})$. The **Walsh function** w_A is defined by

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Theorem

$(w_A)_{A \in \mathcal{P}_f(\mathbb{N})}$ is an orthonormal basis of $L^2(\{-1, 1\}^\mathbb{N}, \nu)$.

A new γ -radonifying operator

Lemma

Let $\phi : \{-1, 1\}^{\mathbb{N}} \rightarrow \mathcal{C}$ be an homeomorphism and let σ be the image of the Haar measure ν on $\{-1, 1\}^{\mathbb{N}}$ by ϕ . Let $u : \{-1, 1\}^{\mathbb{N}} \rightarrow X$ be a continuous function such that, for any $n \geq 1$, for any $(s_1, \dots, s_{n-1}) \in \{-1, 1\}^{n-1}$, any $s', s'' \in \{-1, 1\}^{\mathbb{N}}$,

$$\|u(s_1, \dots, s_{n-1}, 1, s') - u(s_1, \dots, s_{n-1}, -1, s'')\| \leq 3^{-n}.$$

Let also $E = u \circ \phi^{-1}$. Then there exists an orthonormal basis (e_n) of $L^2(\mathbb{T}, d\sigma)$ such that the operator $K_E : L^2(\mathbb{T}, d\sigma) \rightarrow X$ satisfies

$$\sum_n \|K_E(e_n)\| < +\infty.$$

What remains to be done

- Prove that, if T admits a perfectly spanning \mathbb{T} -eigenvector field, then one can construct $\phi : \mathcal{C} \rightarrow \mathbb{T}$, $u : \mathcal{C} \rightarrow X$ such that

$$\|u(s_1, \dots, s_{n-1}, 1, s') - u(s_1, \dots, s_{n-1}, -1, s'')\| \leq 3^{-n}$$

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- Prove that everything remains true with $K_E : L^2(\mathbb{T}, d\sigma) \rightarrow X$ instead of $K_E : L^2(\mathbb{T}, dm) \rightarrow X$.

In fact, we will have to consider several such maps instead of one!

The construction of Cantor sets

Lemma

Let $T \in \mathcal{L}(X)$ with a perfectly spanning \mathbb{T} -eigenvector field. Let also (ε_n) be a sequence of positive real numbers. There exist a sequence (C_i) of subsets of \mathbb{T} , a sequence of homeomorphisms (ϕ_i) from $\{-1, 1\}^{\mathbb{N}}$ onto C_i and a sequence of continuous functions (u_i) , $u_i : \{-1, 1\}^{\mathbb{N}} \rightarrow S_X$ such that, setting $E_i = u_i \circ \phi_i^{-1}$,

- (a) for any $i \geq 1$ and any $\lambda \in C_i$, $TE_i(\lambda) = \lambda E_i(\lambda)$;
- (b) $\text{span}(E_i(\lambda); i \geq 1, \lambda \in C_i)$ is dense in X ;
- (c) for any $n \geq 1$, any $(s_1, \dots, s_{n-1}) \in \{-1, 1\}^{n-1}$, any $s', s'' \in \{-1, 1\}^{\mathbb{N}}$,

$$\|u_i(s_1, \dots, s_{n-1}, 1, s') - u_i(s_1, \dots, s_{n-1}, -1, s'')\| \leq \varepsilon_n.$$

How to prove this?

Step 1 Since E has a perfectly spanning \mathbb{T} -eigenvector field, there exists a sequence (x_i) satisfying :

- each x_i belongs to S_X , is a \mathbb{T} -eigenvector and the corresponding eigenvalues (λ_i) are all different;
- each x_i is a limit of a subsequence $(x_{n_k})_{k \geq 1}$;
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Step 2 The construction...

Proof of the main result

We apply the previous lemma with $\varepsilon_n = 3^{-n}$. We get \mathcal{C}_i , u_i , E_i , σ_i and an orthonormal basis of $L^2(\mathbb{T}, d\sigma_i)$ such that

$$\sum_n \|K_{E_i}(e_{n,i})\| < +\infty.$$

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We set $\mathcal{H} = \oplus_{i \geq 1} L^2(\mathbb{T}, d\sigma_i)$ and let $K : \mathcal{H} \rightarrow X$ be defined by

$$K(\oplus_i f_i) = \sum_i \alpha_i K_{E_i}(f_i)$$

where (α_i) satisfies

(a) $\sum_i \alpha_i^2 \|E_i\|_{L^2(\mathbb{T}, \sigma_i, X)}^2 < +\infty$

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Everything works with $R = KK^*$.

The correct statement

In fact, we have obtained the following statement:

Theorem

Let $T \in \mathfrak{L}(X)$ be such that, for any $D \subset \mathbb{T}$ countable, $\ker(T - \lambda I; \lambda \in \mathbb{T} \setminus D)$ is a dense subset of X . Then there exists a Gaussian measure μ on X with full support, with respect to which T is a weakly-mixing measure-preserving transformation.

Example - backward weighted shifts

Let $B_{\mathbf{w}}$ be the **weighted backward shift** on $\ell^p(\mathbb{N})$ with weight sequence (w_n) :

$$B_{\mathbf{w}}(x_0, x_1, \dots) = (w_1 x_1, w_2 x_2, w_3 x_3, \dots).$$

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There exists a Gaussian measure μ on $\ell^p(\mathbb{N})$ with full support, with respect to which $B_{\mathbf{w}}$ is a measure-preserving and weakly mixing transformation.

Example - backward weighted shifts

The condition

$$\sum_{n \geq 1} \frac{1}{(w_1 \cdots w_n)^p} < \infty.$$

ensures that $B_{\mathbf{w}}$ admit \mathbb{T} -eigenvectors:

$$E(\lambda) := \sum_{n \geq 0} \frac{\lambda^n}{w_1 \cdots w_n} e_n.$$

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This eigenvector field is perfectly spanning.

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$$\langle y, E(\lambda) \rangle = 0 \text{ a.e..}$$

Then

$$g(\lambda) = \sum_n \frac{y_n}{w_1 \cdots w_n} \lambda^n = 0 \text{ a.e..}$$

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$$\implies \hat{g}(n) = 0 \text{ for all } n \in \mathbb{N}.$$

Example - Adjoint of multipliers

$$\begin{aligned} H^2(\mathbb{D}) &= \left\{ f : \mathbb{D} \rightarrow \mathbb{C}; \|f\|_{H^2}^2 := \sup_{r < 1} \int_{-\pi}^{\pi} |f(re^{i\theta})|^2 \frac{d\theta}{2\pi} < \infty \right\} \\ &= \left\{ f(z) = \sum_n a_n z^n; \sum_n |a_n|^2 < +\infty \right\}. \\ H^\infty(\mathbb{D}) &= \{f : \mathbb{D} \rightarrow \mathbb{C}; \|f\|_\infty < +\infty\}. \end{aligned}$$

Definition

For $\phi \in H^\infty(\mathbb{D})$, the multiplier M_ϕ is defined by $M_\phi(f) = \phi f$, $f \in H^2(\mathbb{D})$.

Theorem

If ϕ is non-constant and $\phi(\mathbb{D}) \cap \mathbb{T} \neq \emptyset$, then there exists a Gaussian measure with full support on $H^2(\mathbb{D})$ with respect to which M_ϕ^ is a measure-preserving and weakly mixing transformation.*

Adjoints of multipliers

Let k_z be the **reproducing kernel** at $z \in \mathbb{D}$:

$$\forall f \in H^2(\mathbb{D}) : f(z) = \langle f, k_z \rangle_{H^2} .$$

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$$\langle f, M_\phi^*(k_z) \rangle_{H^2} = \langle \phi f, k_z \rangle_{H^2} = \phi(z)f(z) = \langle f, \overline{\phi(z)}k_z \rangle_{H^2}.$$

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When $\phi(\mathbb{D}) \cap \mathbb{T} \neq \emptyset$, one can find an open arc $I \subset \mathbb{T}$ and a curve $\Gamma \subset \mathbb{D}$ such that $\phi(\Gamma) = I$.

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$$E(e^{i\theta}) := \mathbf{1}_I(e^{i\theta})k_{\phi^{-1}(e^{i\theta})}.$$

is a (conjugate) \mathbb{T} -eigenvector field.

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$$f \equiv 0.$$

And so on...

- Many other examples (composition operators,...);
- Many other results (about the converse, on semigroups of operators,...)

Muchas gracias!